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VIDEO REPRODUCING METHOD AND VIDEO REPRODUCING APPARATUS

5 This application is based upon and claims the
benefit of priority from the prior Japanese Patent
Application No. 2000-054598, filed February 29, 2000,
the entire contents of which are incorporated herein by
reference.

The present invention relates to a method and apparatus for reproducing an encoded video signal, and more particularly, to an improved method and apparatus for reproducing an encoded video signal to produce a smooth video signal.

Generally, in these decoders, after a video signal
25 is decoded, a post filter filters the decoded video
signal to improve the image quality. Most coding
schemes such as MPEG-2/MPEG-4 process video images in

blocks, which degrades the decoded image with block noise and edge noise. Block noise is distortion in the decoded signal that appears as block patterns that are not present in the original video image. Edge noise is
5 ringing-like noise (also referred to as "mosquito noise") that occurs near edges.

The post filter removes such noises inherent in the coding scheme. The post filter smoothes a decoded video signal to remove high frequency components in a
10 boundary region between blocks. A decoding apparatus that has such a post filter is known, for example, from Japanese Patent Publication (KOKAI) No. 64-55987. This document discloses a method of first determining whether a block of a video signal output from a decoder
15 is a dynamic block, which includes movements, or a static block, which does not include movements, and then changing the degree of smoothing in the post filter based on this determination to improve the efficiency of the processing. More specifically, if
20 the block is a static block, then smoothing is not performed or hardly performed on the static block. Conversely, if the block is a dynamic block, then smoothing is performed on the dynamic block.

The above method requires excessive time to
25 perform a relatively large amount of calculations, resulting in a delay in the reproduction of the video signal. For example, in a microprocessor-based system

that uses software for decoding, decoding a scene that includes rapid movements uses up the processor resource. This causes frequent reproduction delays. These delays are particularly prominent when a video is decoded and reproduced in software in synchronism with audio, resulting in problems such as discrepancy with the audio and dropped frames.

More specifically, when there is a delay in the reproduction of a video signal, frame skipping is typically performed to compensate for the delay, causing decoding to be omitted for several frames. This results in dropped frames, which makes a reproduced image distorted.

Also, in the above referenced patent publication, smoothing is omitted for static blocks even if the processor is available, resulting in unnecessarily degraded image quality.

BRIEF SUMMARY OF THE INVENTION

Accordingly, the present invention is directed to method and apparatus that substantially obviates one or more of the problems due to limitations and disadvantages of the related art.

In accordance with the purpose of the invention, as embodied and broadly described, the invention is directed to a method for reproducing an encoded video signal comprising decoding the encoded video signal to produce a decoded video signal, detecting a

reproduction condition, and processing the decoded video signal based on the reproduction condition.

Also, in accordance with the present invention, there is provided an apparatus for reproducing an
5 encoded video signal comprising a decoder configured to decode an encoded video signal, at least one filter configured to filter the decoded video signal, a detector configured to detect a reproduction condition, and a controller configured to control the at least one
10 filter based on the detected reproduction condition.

Further in accordance with the present invention there is provided an article of manufacture comprising a computer usable medium having computer readable program code means embodied therein for reproducing an
15 encoded video signal. The computer readable program code means comprises first computer readable program code means for causing a computer to decode the encoded video signal, second computer readable program code means for causing the computer to perform a filter
20 processing on the decoded video signal, third computer readable program code means for causing the computer to detect a reproduction condition, and fourth computer readable program code means for causing the computer to control the filter processing based on the detected
25 reproduction condition.

Additional advantages of the present invention will be set forth in the description which follows, and

in part will be obvious from the description, or may be learned by practice of the present invention.

The advantages of the present invention may be realized and obtained by means of the instrumentalities
5 and combinations particularly pointed out hereinafter.

BRIEF DESCRIPTION OF THE SEVERAL VIEWS OF THE DRAWING

The accompanying drawings, which are incorporated in and constitute a part of the specification,
illustrate presently preferred embodiments of the
10 present invention and, together with the general description given above and the detailed description of the preferred embodiments given below, serve to explain the principles of the present invention in which:

FIG. 1 is a block diagram illustrating a computer
15 system according to an embodiment of the present invention;

FIG. 2 is a diagram for explaining a basic function of a video reproduction software used in the computer system of FIG. 1;

20 FIG. 3 is a diagram illustrating the configuration of a video reproduction software used in the computer system of FIG. 1;

FIG. 4 is a diagram illustrating the functional configuration of a reproduction engine unit used in the
25 video reproduction software of FIG. 3;

FIG. 5 is a diagram illustrating an exemplary structure of a stream of AV signals for use in the

embodiment shown in FIG. 1;

FIG. 6 is a flow chart illustrating reproduction delay notification processing used in the embodiment shown in FIG. 1;

5 FIG. 7 is a diagram illustrating the functional configuration of a video decoder provided in the reproduction engine unit of FIG. 4;

FIG. 8 is a flow chart illustrating a first example of delay detection processing used in the
10 embodiment shown in FIG. 1;

FIG. 9 is a flow chart illustrating a first example of decoding control processing used in the embodiment shown in FIG. 1;

FIG. 10 is a flow chart illustrating a second
15 example of delay detection processing used in the embodiment shown in FIG. 1;

FIG. 11 is a flow chart illustrating a second example of decoding control processing used in the embodiment shown in FIG. 1;

20 FIG. 12 is a flow chart illustrating a third example of delay detection processing used in the embodiment shown in FIG. 1; and

FIG. 13 is a flow chart illustrating a third example of decoding control processing used in the
25 embodiment shown in FIG. 1.

DETAILED DESCRIPTION OF THE INVENTION

Embodiments consistent with the present invention

provide a video reproducing method and apparatus that are capable of minimizing the occurrence of frame skipping to reproduce a smooth and high quality video.

Method and apparatus consistent with the present
5 invention decode an encoded video signal, filter the decoded video signal, and control the filtering based on a reproduction condition.

Since the filtering is controlled based on a reproduction condition, it is possible to perform
10 optimal filtering for the reproduction condition. By optimizing the filtering, the amount of processing can be adjusted based on a load on a processor without requiring such processing as frame skipping, thereby making it possible to realize a smooth video.

15 Reproduction delay can be used as the reproduction condition. When a reproduction delay is detected, the reproduction delay can be recovered by omitting the filtering of the decoded video signal or changing the type of filtering to a simpler one that requires less
20 processing. This prevents frames from dropping due to frame skipping. It is therefore possible to reproduce a smooth video even in a scene including rapid movements. Although omitting the filtering or changing the type of filtering reduces the image quality, the
25 image quality is better than the resulting image quality when a frame is skipped.

Also, by using a state variable to manage the

reproduction delay, image quality degradation can be minimized by utilizing multi-stage control, which involves switching the type of filtering to one requiring less processing in a stepwise manner based on the delay and eventually omitting the filtering of the decoded video signal.

Further, the foregoing filtering control and frame skipping may be combined such that the filtering is controlled while the reproduction delay remains within a certain fixed range and the decoding is omitted for a predetermined number of frames when the delay reaches a predetermined value, thereby making it possible to simultaneously accomplish reproduction of a smooth video and normal reproduction free from a failure.

An embodiment of a video reproducing method and a video reproducing apparatus according to the present invention will now be described with reference to the accompanying drawings.

FIG. 1 illustrates an exemplary video reproducing apparatus according to an embodiment of the present invention that employs a personal computer. The illustrated personal computer is a notebook type portable computer system that is capable of decoding and reproducing in software an audio/video stream that has been encoded using a coding scheme such as MPEG-2/MPEG-4.

The computer system comprises a CPU 11; a HOST/PCI

bridge 12; a main memory 13; a display controller 14; a sound controller 15; a communication interface 16; an I/O controller 17; a PCI/ISA bridge 18; a camera 20; a hard disk drive (HDD) 21; and a DVD drive 22.

5 The CPU 11, which is provided to control the overall system, executes an operating system and a variety of other application programs, which are loaded into the main memory 13. A video reproduction software 100 is used as a program for decoding an audio/video
10 stream for reproduction. The video reproduction software 100 supports AV (audiovisual) data in a variety of compression schemes such as MPEG-2, MPEG-4, AVI, and DVI, and is capable of reading a file of encoded AV data and decoding it for reproduction.

15 The HOST/PCI bridge 12, a bus bridge that interconnects a CPU bus 1 and a PCI bus 2, contains a memory control logic for controlling the main memory 13. The display controller 14 controls an LCD or an
20 external CRT display that is used as a display monitor for the computer system. For reproducing AV data, a decoded video signal produced by the video reproduction software 100 is displayed on the display monitor through the display controller 14.

 The sound controller 15, which is used as a sound
25 source, inputs and outputs a variety of audio data. For reproducing AV data, a decoded audio signal produced by the video reproduction software 100 is

reproduced from a speaker through the sound controller 15, or output to external audio equipment from a line out terminal.

5 The communication interface 16 communicates with the external or built-in camera 20 in accordance with a serial interface standard, such as USB or IEEE 1394, and fetches video data or image data from the camera 20. The video data or image data signal captured by the camera 20 may be reproduced for display as it is, or
10 recorded on a variety of recording media such as the HDD 21, the DVD drive 22, or a memory card 23, through the I/O controller 17 after it is compressed in accordance with a coding scheme such as MPEG-2, MPEG-4, AVI, or DVI.

15 The PCI/ISA bridge 18, a bus bridge that interconnects the PCI bus 2 and an ISA bus 3, contains a variety of system devices such as a real time clock (RTC) 181. The real time clock (RTC) 181 is a timer module that provides the time used in this embodiment
20 to manage a delay in the processing for reproducing AV data.

Video Reproduction Software

Basic functions of the video reproduction software 100 will now be described with reference to FIGS. 2
25 and 3.

As described above, the video reproduction software 100 can read a file of encoded AV data

recorded in storage media such as the HDD 21, the DVD
drive 22, and the memory card 23, and decode the
encoded AV data for reproduction. FIG. 2 illustrates
how an encoded AV file 210 recorded in the HDD 21 is
5 decoded for reproduction.

The encoded AV file 210 is produced by compressing
a video signal and an audio signal in digital form, and
multiplexing encoded bit streams representative of
these signals. The video reproduction software 100
10 retrieves the encoded AV file 210 from the HDD 21,
separates the encoded AV file 210 into a video signal
and an audio signal, decodes the signals, and displays
the video signal on the display monitor while
reproducing the audio signal from a speaker, for
15 example.

As illustrated in FIG. 3, the video reproduction
software 100 comprises an application program 101 and a
reproduction engine 102. The application program 101
has a user interface for the processing involved in the
video production and an interface for controlling the
20 reproduction engine 102. The application program 101
instructs the reproduction engine 102 to perform
operations required for reproducing the encoded AV file
210 specified by the user. The reproduction engine 102,
25 a platform implemented on an operating system (OS) 103
for multimedia processing, comprises a group of various
program modules (filters) for performing the processing

required for video and audio reproduction, as exemplified by input/output processing and rendering for video/audio reproduction. These modules can be used in an arbitrary combination by an instruction from
5 the application program 101.

Reproduction Engine

Next, the reproduction engine 102 will be described in terms of its functional configuration. FIG. 4 illustrates the configuration of the modules of
10 the reproduction engine 102 during reproduction of an encoded AV file.

Video and audio data included in an encoded AV file is reproduced by linking a manager 301, a file reader 302, a demultiplexer (DMUX) 303, a video decoder
15 304, a video renderer 305, an audio decoder 306, and an audio renderer 307 as illustrated.

First, file reader 302 reads an encoded file containing an encoded bit stream and sends the encoded bit stream to the demultiplexer (DMUX) 303. DMUX 303
20 separates the encoded bit stream into video data and audio data.

The video data is separated in frames in the demultiplexer (DMUX) 303 and sent to the video decoder 304 on a frame-by-frame basis. The video decoder 304
25 includes an image expansion function and a filtering function for improving the image quality of a decoded signal. A decoded video image produced by the video

decoder 304 is sent to the display controller 14 through the video renderer 305 and reproduced for display on a monitor. The audio data, on the other hand, is decoded by the audio decoder 306, and sent to the sound controller 15 through the audio renderer 307 for reproduction from a speaker, for example.

As shown in FIG. 5, one block of encoded video data comprises a block header and a data stream, which includes a plurality of frames and a time stamp TS embedded at the beginning of each frame. Using the time stamp TS, the manager 301 monitors the frame rate of a reproduced signal (i.e., the reproduction speed) by comparing an elapsed time from the beginning of reproduction with a time stamp of a frame that is being reproduced. A reproduction delay occurs when the frame rate of a reproduced signal is lower than the original frame rate. When this delay occurs, the manager 301 notifies the video renderer 305 of the delay. The notification is referred to as a reproduction delay notification. The reproduction delay notification is communicated from the video renderer 305 to upstream modules in order. In other words, a reproduction condition is communicated to the video decoder 304, for example, through the video renderer 305.

25 Reproduction Delay Notification

FIG. 6 illustrates a processing procedure for the manager 301 to issue the reproduction delay

notification. Upon starting the reproduction of the AV file, the manager 301 acquires the time (start time) from the RTC 181 (step S11). Then, the manager 301 periodically acquires a current time from the RTC 181 (step S12) to determine an elapsed time from the start time. The manager 301 compares the elapsed time with a time stamp of a frame being reproduced and calculates the reproduction delay (step S13). While the time stamp of a frame being reproduced may be acquired from the video renderer 305, the time stamp of a frame several frames after the frame being reproduced may be acquired from the demultiplexer (DMUX) 303 and converted to the value of the time stamp in the frame being reproduced. For encoded data in AVI format, the header including the time stamp is included in a stream that is compressed, for example, in accordance with MPEG-2/MPEG-4, so that a time stamp in AVI format may be utilized instead of the time stamp unique to MPEG-2/MPEG-4.

20 The calculated reproduction delay is converted to a value representing a reproducing speed, which is then notified to the video renderer 305 (step S14). For example, the value representing the reproducing speed equals 100% when the reproducing speed is at a normal speed. The value decreases as the amount of delay increases.

Video Decoder

Next, the configuration of the video decoder 304 will be described with reference to FIG. 7.

The video decoder 304, one module within the reproduction engine 102, comprises an image expansion unit 501; an image quality improving unit (post filter) 502; an image output unit 503; a delay detector 504; a state variable 505; and a controller 506, as illustrated. The image expansion unit 501, the image quality improving unit 502, and the image output unit 503 form a decoding unit for decoding an encoded video signal.

The image expansion unit 501 decodes compressed video, performing processing such as a variable length decoding, inverse-quantization, inverse-DCT, motion compensation prediction, and addition of a predicted image to a differentially decoded image for a video signal compressed in accordance with MPEG-2/MPEG-4. As one frame of a decoded image is produced by the image expansion unit 501, the decoded image is sent to the image quality improving unit 502.

The image quality improving unit 502, a post filter, implements smoothing filtering to reduce block noise to improve the image quality of the decoded image. The image quality improving unit 502 applies to the decoded video signal a variety of filters with different processing speeds and filtering magnitudes by

switching the type of filter (IIR filter, FIR filter)
and setting filter parameters. Here, since the
smoothing filtering is an example of processing for
adjusting the image quality, it will hereinafter be
5 referred to as "filtering", including a variety of
other image quality adjusting processing.

The controller 506 controls the filtering
performed by the image quality improving unit 502.

The image output unit 503 outputs a decoded image
10 processed by the image quality improving unit 502 to
the video renderer 305. The delay detector 504, which
detects a reproduction delay for a video signal with a
delay notification communicated from the manager 301
through the video renderer 305, manages a reproduction
15 delay as a current reproducing condition using the
state variable 505.

The controller 506, which controls the operation
of the decoding unit, implements control for optimal
filtering by the image quality improving unit 502.
20 Specifically, the controller 506 performs delay
recovery control to recover the reproduction delay by
omitting the filtering performed by the image quality
improving unit 502 based on the value of the state
variable 505 or switching the type of filtering to a
25 simpler one with a smaller amount of processing. This
eliminates the need for omitting the decoding performed
by the image expansion unit 501 (i.e., frame skipping).

In the following, a specific procedure will be described for the delay recovery control processing.

First Delay Recovery Control

A first example of the delay recovery control processing will be described with reference to FIGS. 8 and 9. In this example, the controller 506 performs delay recovery control processing based on the binary state variable 505. If the binary state variable 505 equals "1", then the controller 506 performs delay recovery control processing by omitting the filtering performed by the image quality improving unit 502. If the binary state variable 505 equals "0", then the controller 506 does not perform delay recovery control processing.

FIG. 8 is a flow chart illustrating delay detection by the delay detector 504. As illustrated in FIG. 8, upon receipt of a reproduction delay notification from the manager 301 through the video renderer 305, the delay detector 504 first determines whether the reproduction delay is larger than a predetermined amount based on the value of a reproducing speed (%) specified by the reproduction delay notification as the amount of delay (step S311). If the reproduction delay is less than or equal to the predetermined amount (NO at step S311), the processing is terminated without performing anything.

However, if the reproduction delay is larger than

the predetermined amount (YES at step S311), the delay detector 504 checks the current value of the state variable 505 (step S312).

5 If the state variable is equal to "0" (YES at step S312), the delay detector 504 changes the value of the state variable to "1" to notify the controller 506 that delay recovery processing is required (step S313). If the state value is equal to "1" (NO at step S312), the processing is terminated without performing anything.

10 In this way, the state variable is set to "1" when the current reproduction delay is large enough to require the delay recovery, and otherwise to "0."

FIG. 9 is a flow chart illustrating control processing by the controller 506 for each frame. First,

15 the image expansion unit 501 performs decoding on a frame of interest (step S351). At the time the decoding is completed for one frame, the controller 506 checks the state variable 505 (step S352). If the state variable 505 is "0" (NO at step S352), the

20 controller 506 delivers the one frame of the decoded image signal to the image quality improving unit 502, as it normally does, forcing the image quality improving unit 502 to perform a predetermined smoothing filtering for improving the image quality (step S353).

25 Then, the filtered image signal is output from the image output unit 503 (step S354).

However, if the state variable is "1" (YES at step

S352), the controller 506 skips the filtering which would otherwise be performed by the image quality improving unit 502 for improving the image quality and outputs the decoded image signal as it is from the
5 image output unit 503 (step S354).

In this way, a smooth and high quality video can be reproduced by optimally controlling the filtering without omitting the decoding itself (i.e., without skipping frames/frame dropping), even if the
10 reproduction is delayed due to a heavily loaded processor that is used up by the decoding of a scene including rapid movements.

Second Delay Recovery Processing

Next, a second example of the delay recovery
15 control processing will be described with reference to FIGS. 10 and 11. In this example, to manage a reproduction delay, the controller 506 relies on a four-value state variable 505, which may equal "0", "1", "2", or "3", to change the filtering in a stepwise
20 manner.

FIG. 10 is a flow chart illustrating delay detection processing by the delay detector 504. As illustrated in FIG. 10, upon receipt of a reproduction delay notification from the manager 301 through the
25 video renderer 305, the delay detector 504 first determines whether the reproduction delay is larger than a predetermined amount based on the value of a

reproducing speed (%) specified by the reproduction delay notification as the amount of delay (step S411).

If the reproduction delay is less than or equal to the predetermined amount (NO at step S411), the delay

5 detector 504 terminates processing without performing anything. However, if the reproduction delay is larger than the predetermined amount (YES at step S411), the delay detector 504 checks the current value of the state variable 505 (step S412).

10 If the state variable is lower than the highest value "3" (YES at step S412), the delay detector 504 increments the value of the state variable indicative of the degree of the delay by +1 (step S413). However, if the state variable equals the highest value "3" (NO
15 at step S412), the delay detector 504 terminates processing without performing anything. In this way, the state variable increases as the current reproduction delay increases.

FIG. 11 is a flow chart illustrating control
20 processing by the controller 506 for each frame. First, the image expansion unit 501 decodes a frame of interest (step S451). At the time the decoding is completed for one frame, the controller 506 checks the state variable 505 (step S452) to change the filter
25 based on the value of the state variable 505. In this example, three filtering processes, "A", "B", and "C" having different loads of processing, are provided.

The filtering process "A" provides the highest level of image quality improvement, but requires a longer processing time. The filtering process "B" provides the second highest level of image quality improvement; and the filtering process "C", the lowest level. The CPU 11 is loaded more heavily with the filtering in the following order of the filtering processes: "C", "B", "A".

If the state variable equals "0", the controller 506 delivers the one frame of decoded image to the image quality improving unit 502, forcing the image quality improving unit 502 to perform the most time intensive filtering process "A" (step S453). Then, the filtered video signal is output from the image output unit 503 (step S456). Similarly, the controller 506 forces the image quality improving unit 502 to perform the filtering process "B" if the state variable equals "1" and to perform least time intensive filtering process "C" if the state variable equals "2" (steps S454 and S455). However, if the state variable equal the highest value "3", the controller 506 forces the image quality improving unit 502 to skip the filtering for improving the image quality and outputs the decoded image as it is from the image output unit 503 without performing the filtering (step S456).

In this way, a smooth and high quality video without frame dropping can be reproduced free from

sudden changes in the image quality. This is achieved by controlling the image quality improving unit 502 to degrade the contents of the filtering gradually in accordance with the delay and to eventually skip the
5 filtering.

Third Delay Recovery Control

Next, a third example of the delay recovery control processing will be described with reference to FIGS. 12 and 13. In this example, a three-value state
10 variable 505, which may equal "0", "1", or "2", determines whether filtering and/or frame skipping will be performed.

FIG. 12 is a flow chart illustrating the delay detection processing by the delay detector 504. As
15 illustrated in FIG. 12, upon receipt of a reproduction delay notification from the manager 301 through the video renderer 305, the delay detector 504 first determines whether the reproduction delay is larger than a predetermined amount based on the value of a
20 reproducing speed (%) specified by the reproduction delay notification as the amount of delay (step S511). If the reproduction delay is less than or equal to the predetermined amount (NO at step S511), the delay detector 504 terminates processing without performing
25 anything. However, if the reproduction delay is larger than the predetermined amount (YES at step S511), the delay detector 504 checks the current value of the

state variable 505 (step S512).

If the state variable is lower than the highest value "2" (YES at step S512), the delay detector 504 increments the value of the state variable indicative of the degree of the delay by +1 (step S513). However, if the state variable equals the highest value "2" (NO at step S512), the delay detector 504 terminates processing without performing anything. In this way, the state variable increases as the current reproduction delay increases.

FIG. 13 is a flow chart illustrating control processing by the controller 506 for each frame. Before the image expansion unit 501 decodes a frame, the controller 506 first checks the state variable 505 (step S551). If the state variable 505 equals the highest value "2" (YES at step S511), the decoding, the filtering, and the image output are all skipped, thereby skipping a frame.

However, if the state variable 505 is less than or equal to "1" (NO at step S511), the controller 506 forces the image expansion unit 501 to decode a frame of interest (step S552) and then determines whether the state variable equals "0" or "1" (step S553). If the state variable equals "0" (NO at step S553), the controller 506 delivers the one frame of decoded image to the image quality improving unit 502, as it normally does, forcing the image quality improving unit 502 to

perform the smoothing filtering for improving the image quality (step S554). Then, the filtered video signal is output from the image output unit 503 (step S555). However, if the state variable equals "1" (YES at step
5 S553), the controller 506 forces the image quality improving unit 502 to skip the filtering for improving the image quality and outputs the decoded image as it is from the image output unit 503 without performing the filtering (step S555).

10 In this way, the reproduction of a smooth video and the reproduction of a high quality image can be simultaneously achieved by omitting the filtering when the reproduction delay is within a certain fixed range and by skipping a frame when the delay exceeds the
15 certain range (of course, the filtering is also skipped).

The control processing illustrated in FIG. 13 may also be applied in the aforementioned examples. For example, in the second example, the filtering can be
20 controlled in a stepwise manner when the reproduction delay is within a certain fixed range as describe above with reference to FIG. 11. However, in addition, a frame can be skipped when the delay exceeds the fixed range.

25 As described above, since a load on a CPU is reduced by controlling the filtering when an increase in a load on the CPU causes a reproduction delay, an

image quality adjustment can be optimized based on the load of the CPU, thereby limiting frame skipping, even when a video is decoded in software for reproduction in synchronism with audio.

5 While the foregoing embodiments have shown an example in which the reproduction delay notification is generated by comparing a time stamp in a frame being reproduced with an elapsed time from the start of reproduction, the degree of delay in reproduction may
10 be detected, for example, based on the amount of occupied buffer, which is controlled in terms of the rate, to control the contents of filtering in accordance with the degree of delay thus detected.

 Also, while the foregoing embodiments have not
15 explicitly described specific processing for decrementing the state variable, the value of the state variable may of course be decremented if a delay in reproduction is reduced.

 Further, the software-based decoding method
20 according to the foregoing embodiments can be readily implemented by introducing a computer program including the procedure into a normal computer through a computer readable recording medium. In addition, the methods may be applied to such devices as a game machine, a
25 digital television set, or a set top box, as well as to a computer.

 As described above, according to the present

invention, the filtering for improving the image quality of a decoded image can be controlled to eliminate the frame skipping, thereby making it possible to reproduce a smooth video.

5 Additional advantages and modifications will readily occur to those skilled in the art. Therefore, the present invention in its broader aspects is not limited to the specific details, representative devices, and illustrated examples shown and described herein.

10 Accordingly, various modifications may be made without departing from the spirit or scope of the general inventive concept as defined by the appended claims and their equivalents.